

By default all nodes (except coordinators) are set up to check whether any neighbours on the same PAN are around, or they have orphaned once every minute.

If no neighbours have been found after a couple of minutes, the unit will leave the (deserted) PAN and try to join into a new one once every minute.

This initial network setup can take a few minutes, especially with no serial access to remote nodes, but once the network is set up it will remain set even after power cycles.

New nodes joining will in cause a prompt '**NEWNODE: <EUI64>**' on the remote side, where <EUI64> is the unique 64 bit identifier of the device joining in and display the **JPAN** message locally as described above.

To learn more about setting up and maintaining a PAN please refer to the User Guide and the AT Command Dictionary.

4 Configuring Buttons for your set-up

After setting up the network, press the button labelled '**Configure**' which will issue a command to scan the network causing all of the nodes in the network to report in. You will see that on discovery of a remote device its serial number is added to the device list window. In addition to this the configure functionality will build additional buttons for you to allow toggling the LEDs ('**Led x on**' and '**LED x off**' in the register access group) on a remote MCB as well as playing a tune on a remote devboard or MCB ('**Ident Node x**' in the test commands group).

By looking at the actual commands behind these new buttons it is quite easy to understand how the AT-Command interface operates. Also you can easily discover the principle of mesh networking. Simply move an MCB (or devboard) out of range and then add an MCB or devboard between the local node and the one which is out of range and you will find that the network has healed the broken link and all three nodes are accessible again.

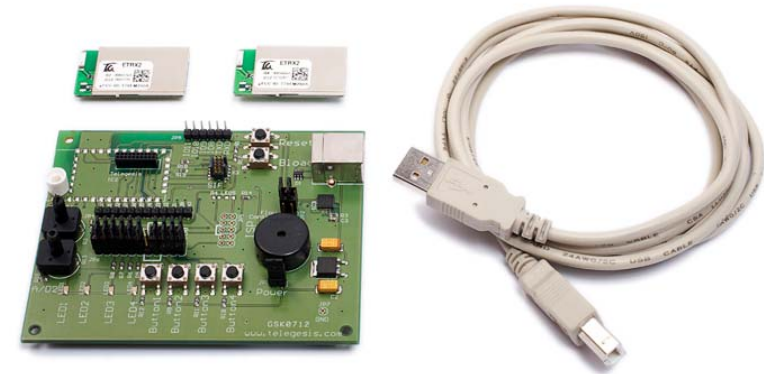
If you have more than a single module connected to a PC try sending messages between the PCs using the Broadcast or Unicast buttons and by playing with those buttons you will quickly get an understanding on how to integrate the ETRX2 into your application.

The Telegesis Terminal Application also allows you to create custom command buttons for your individual application, just click on **Commands / Add command button...**

Telegesis	TG-ETRX2DVKP-QS-01-200	
ETRX2DVKP Development Kit	Dev Kit Quick Start Guide	2.00



ETRX2DVKP Development Kit Quick Start Guide



Your ETRX2DVKP contains:

- A Development Kit board
- An ETRX2HW ZigBee module, to plug on to the Development Kit board
- An ETRX2 module
- A USB cable

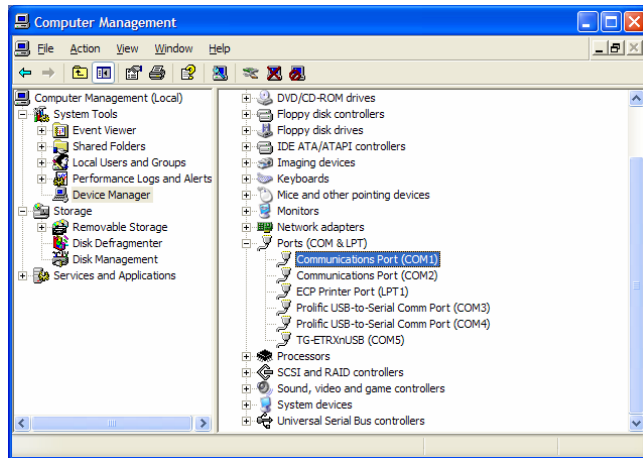
The ETRX2DVKP Development Kit has been designed to allow quick evaluation and prototyping using the ETRX2 wireless mesh networking modules.

Before you start, go to our website software page at www.telegesis.com/ZigBee/Dsoftware.htm and download the ETRX2USB drivers and the Telegesis Terminal software. Install them on your computer. Also, we recommend you to go to www.telegesis.com/ZigBee/Dmanuals.htm

and get the AT Command Manual, the User Guide and the Development Kit Technical Manual. There you will also find all our other product datasheets and manuals.

1 Connecting your Development Kit board

After you have installed the USB drivers, connect the Development Kit board to the computer and load the drivers (this needs to be done twice). Then right-click on “My Computer”, select “Manage” and “Device Manager”.



Under “Ports” you will see your Telegesis USB device; note the COM port number that it is attached to. (here, COM5). Now you can close the Device Manager.

2 Application Software

If you do not wish to use the Telegesis Terminal Application program, the command line of the ETRX2 can be accessed using any terminal software program such as HyperTerminal®. Simply set up HyperTerminal® to connect to the appropriate com port at 19200bps, Data bits - 8, Parity - none, Stop bits - 1, Flow Control – none (ETRX2 factory default).

However the Telegesis Terminal Application Software program allows enhanced functionality especially suited to the ETRX2 modules. The AT-Style commands can be issued by clicking on customisable ‘Command’ buttons and

all of the 64 bit serial numbers which are reporting in are listed in a separate window. This means you will not need to input any of the 64 bit serial numbers.

For instructions on how to use the AT-Commands read the ETRX2 wireless meshing module user guide.

After installing the Telegesis Terminal Application program the command buttons for firmware R2xx based on EmberZnet2.x will be shown at the bottom of the window. In order to use the Telegesis Terminal software, select the correct COM port and the connection parameters (ETRX2 default 19200, 8 bits, no parity, no flow control) and press the “Connect” button. These settings are automatically retained each time the software is re-started.

To get started quickly, power up one node connected to the PC and type **AT** followed by **<enter>**. If the communication to the module is working the module will prompt **OK**, if not check power and serial connections and make sure you have connected to the correct com port.

3 Network Set-up on R2xx firmware

To start a PAN network issue the **AT+EN** command, or alternatively press the ‘**Establish PAN**’ button.

The local unit will now scan all available 16 channels and establish a PAN with a random PAN ID on the quietest one of them. This may take up to 16 seconds and leads to the node becoming the networks coordinator. When successful the module will prompt ‘**JPAN:cc,PPPP**’, where cc is the channel number and PPPP is the PAN ID of the newly created PAN.

If you get an error message instead it is likely that the module was already part of a PAN, so you need to issue the **AT+DASSL** command or press the ‘**Disas Local**’ button to leave the PAN before going back to starting a new one.

In order to find the network status simply issue the **AT+N** command or press the ‘**NWK Info**’ button.

Once the network is established remote nodes can be powered up ready to join in. If you have serial access to remote nodes simply issue the **AT+JN** command or press the ‘**Join any PAN**’ button to join the newly established PAN. If you don’t have serial access to the remote nodes (such as with the two MCBs provided with the DVKA) you just need to wait for them to join the network automatically.